* Explain clearly what is meant by intercept and follow.
* What is the coordinate systems - y is altitude?
* How do the plots in the conclusion help understand/design the system?
* What is the overall objective - intercept/hit the intruder (PN).  Or is it to come close.
* How does the controller get toward the tail of the intruder, and how does the uncertainty circle come into play with this?
* Update references and add meaningful literature references
* Use ICUAS format